

① 4. Geometric design of the track

Grade compensation on curves:-

→ In order to avoid resistances beyond the allowable limits, the gradients are reduced on curves and this reduction in gradients is known as grade compensation for curves.

→ The curve resistance is expressed as per degree.

→ Compensation for curvature is given

$$0.04\text{ f. per degree of curve for BG}$$

$$0.03\text{ f. per degree of curve for MG}$$

$$0.02\text{ f. per degree of curve for NG.}$$

Radius of Curves in meter :- 70/R for BG
Radius of Curves in meter :- 52.5/R for MG
Radius of Curves in meter :- 35/R for NG.

Ques. If the ruling gradient is 1 in 150 on a particular section of BG and at the same time a curve of 4 degrees is situated on this ruling gradient, what should be the allowable ruling gradient?

A) As per, the compensation of BG is $0.04 \frac{\text{f. per degree}}{\text{of curve}}$

$$\text{Then Compensation for } 4^\circ \text{ curve} = 0.04 \times 4 = 0.16 \text{ f.}$$

$$\text{Hence without ruling gradient } 1 \text{ in } 150 = \frac{1}{150} \times 100 = 0.0666 \text{ f.}$$

So max. allowable gradient or actual gradient =

$$0.0666 + 0.16 = 0.2266 \text{ f.}$$

$$\frac{0.2266}{100} = 1 \text{ in } 190 \text{ Ans}$$

Scanned with CamScanner

Ques.

What should be the actual ruling gradient?

(a) If the ruling gradient is 1 in 200 on a BG

(b) A curve of 3° is superimposed on the above track section of BG,

Ques. Speed of the train:-

The speed of the train depends upon the strength of the track and the power of the locomotive.

For BG = 96 km.p.h

MG = 72 km.p.h

NG = 40 km.p.h

With modernization of Indian Railways and use of electric traction it has now become possible to attain train speeds up to 160 km.p.h on BG roads and upto 100 km.p.h on MG roads.

Safe Speed on Curves :-

Safe Speed for all practical purposes means a speed which is safe from the danger of overturning and derailment.

Safe speed on curves depends upon,

(1) Gauge of track (2) Radius of the curve

(3) Amount of super-elevation

(4) Presence and absence of transition curves.

Scanned with CamScanner

(B)

In India following formula given by Marten

Where transition curves exist:-

For B.G and M.G ($V_{Speed} < 100 \text{ kmph}$)

Safe speed V in kmph is given by

$$(i) V = 4.35\sqrt{R-67} \text{ or } V = 4.4\sqrt{R-70} \rightarrow (i) \text{ is for } (i)$$

$$(ii) \text{ For N.G } V = 3.6\sqrt{R-6.1} \text{ or } V = 3.65\sqrt{R-6}$$

* Where transition curves are absent; on non-transitioned curves.

(i) for B.G and M.G

$$V = \frac{4}{5} \text{ th of speed calculated in eq(i)} \\ (\text{say, speed is allowed})$$

$$(ii) \text{ For N.G } = \left(\frac{4}{5} \text{ th of speed calculated in (B) above} \right)$$

$$V = 2.92\sqrt{R-6}$$

$$(iii) \text{ For high speed } - 1 \left(\frac{\text{speed}}{100 \text{ kmph}} \right) \frac{B.G, M.G}{R}$$

$$\text{where } R = 0.14 \text{ and } V = 4.58\sqrt{R}, V = \text{Speed in kmph}$$

$R = \text{Radius of curve in metres.}$

Cent deficiency :-

Cent deficiency = Equilibrium cent necessary for max permissible speed on curve - actual cent provided.

Equilibrium cent :-

When the lateral forces and wheel loads are almost equal, the cent is said to be in equilibrium.

This equilibrium cent is provided on the basis of any speed of the train.

Scanned with CamScanner

(4)

→ Max Cent deficiency for gauges for Indian Railway are

(1) B.G track - 75 mm

(2) M.G track - 50 mm

(3) N.G track - 10 mm

→ Max^m cant deficiency for changes for Indian Railway are

- ① B.G track - 75 mm
- ② M.G track - 50 mm
- ③ N.G track - 40 mm

Radius of curve :-

$$R = \frac{L^2}{2D} = \frac{3600}{2 \times 30} = 300 \text{ m}$$

30 m Chain length

$$D.R.L = 360$$

$$L = \frac{360}{D.R.L}$$

5/51

$$\tan D = \frac{30}{360} = 0.0833$$

$$\tan D = \frac{1.750}{R}$$

- Max^m degree of curvature for B.G = 10° ($\min R = 320m$)
- Max^m degree of curvature for M.G = 16° ($\min R = 109m$)
- Max^m degree of curvature for N.G = 40° ($\min R = 44m$)

Scanned with CamScanner

Super-elevation

Super-elevation or cant :-

To counteract the effect of centrifugal force, the level of the outer rail is raised with respect to inner rail by a certain amount to introduce the centripetal force.

The raised elevation of outer rail above the inner rail at a horizontal curve is called Super-elevation or cant.

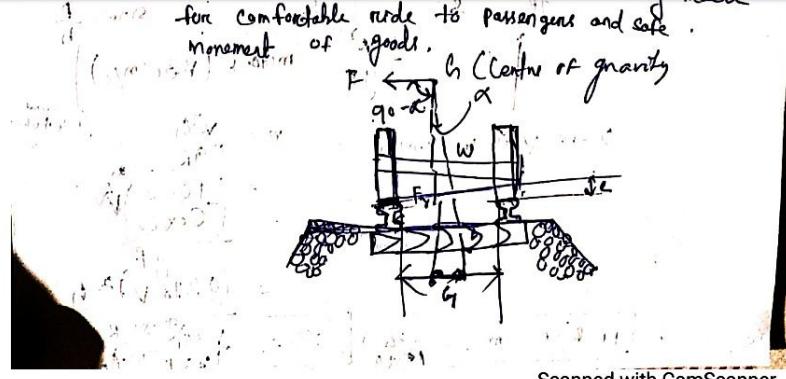
Object of providing super-elevation :-

① To introduce the centripetal force for countering the effect of centrifugal force. This will also prevent derailing and reduce the side wear and creep of rails.

② To provide equal distribution of wheel loads on two rails, so there is no tendency of track to move out of position due to more load on outer rail.

③ To provide an even and smooth running track for comfortable ride to passengers and safe movement of goods.

P → Centre of gravity



Scanned with CamScanner

Relationship of super elevation (e), bank 6/51 Speed (v) and Radius of the curve (R) :-

W = Weight of moving vehicle
 v = Speed of vehicle m/sec
 V = Speed of vehicle kmph
 R = Radius of curve (m)
 h = Hinge of track (m)
 g = Acceleration due to gravity in m/sec²
 α = Angle of inclination.
 S = Length of incline surface in m.

Centrifugal force $F = m \cdot a_{cent}$

Radial acceleration $a = v^2/R$

$$F = \frac{W}{g} \times \frac{v^2}{R} \quad (1)$$

$$F = \frac{Wv^2}{gr} \quad (2)$$

Resolving the forces & weight along inclined line

$$F \cos \alpha = W \sin \alpha \quad \text{means } AC = S$$

$$\frac{Wv^2}{gr} \times \frac{h}{S} = W \times \frac{e}{R} \quad \text{cos} \alpha = \frac{h}{S} \quad \sin \alpha = \frac{e}{R}$$

$$e = \frac{v^2 h}{g R} \quad \text{metres (Km/m/s)}$$

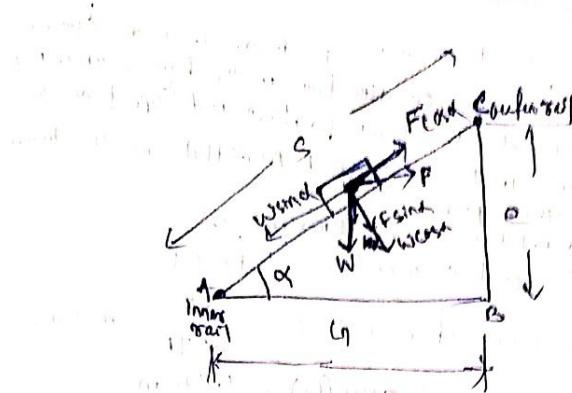
$$\text{When } V \text{ is in kmph.} \quad e = \frac{v^2 h}{g R} \quad (\text{metres})$$

$$= \frac{(1000)^2}{(9.81)(72)} \quad \text{metres}$$

$$= (0.278 V)^2 / 9$$

$$\therefore DF R \text{ in cm} = e = \frac{v^2 h}{g R} \quad e = \frac{v^2 h}{127 R} \quad \text{metres}$$

Scanned with CamScanner



Negative Super-elevation